

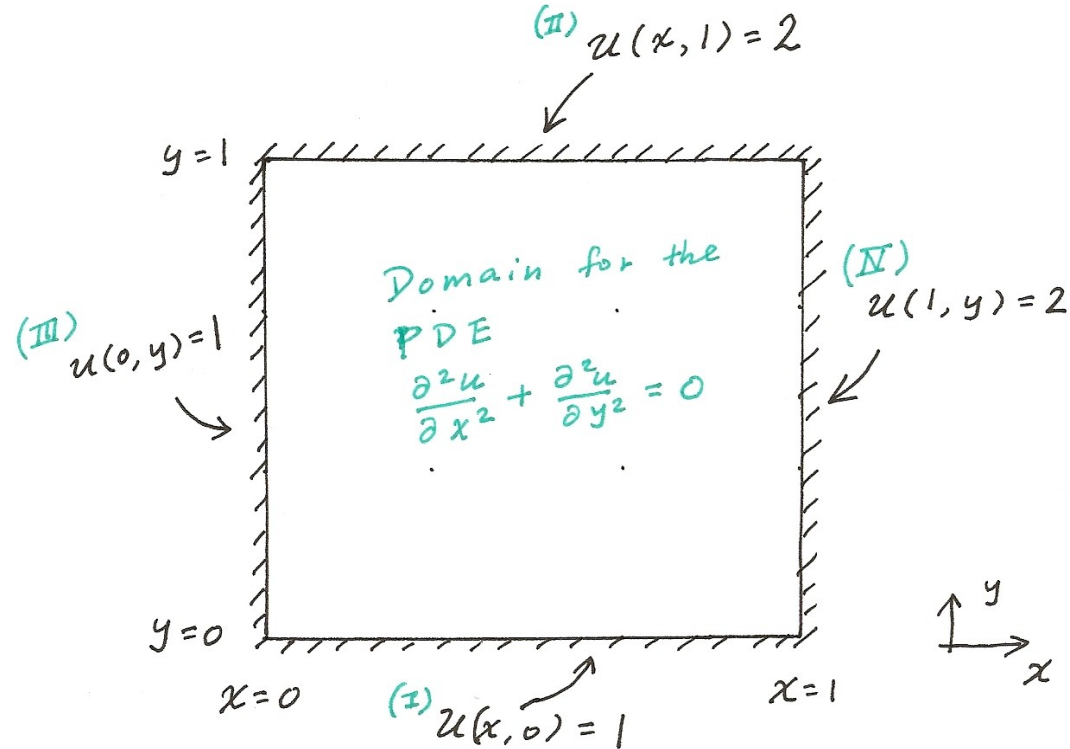
For a boundary value problem with a 2nd order ODE, the two b.c.'s would reduce the degree of freedom from N to $N-2$; We obtain a system of $N-2$ linear equations for the interior points that can be solved with typical matrix manipulations. For an initial value problem with a 1st order ODE, the value of u_0 is given. Then, u_1, u_2, u_3, \dots , are determined successively using a finite difference scheme for du/dx . We will discuss the extension of these two types of problems to PDE in two dimensions.

Case 1: Laplace equation

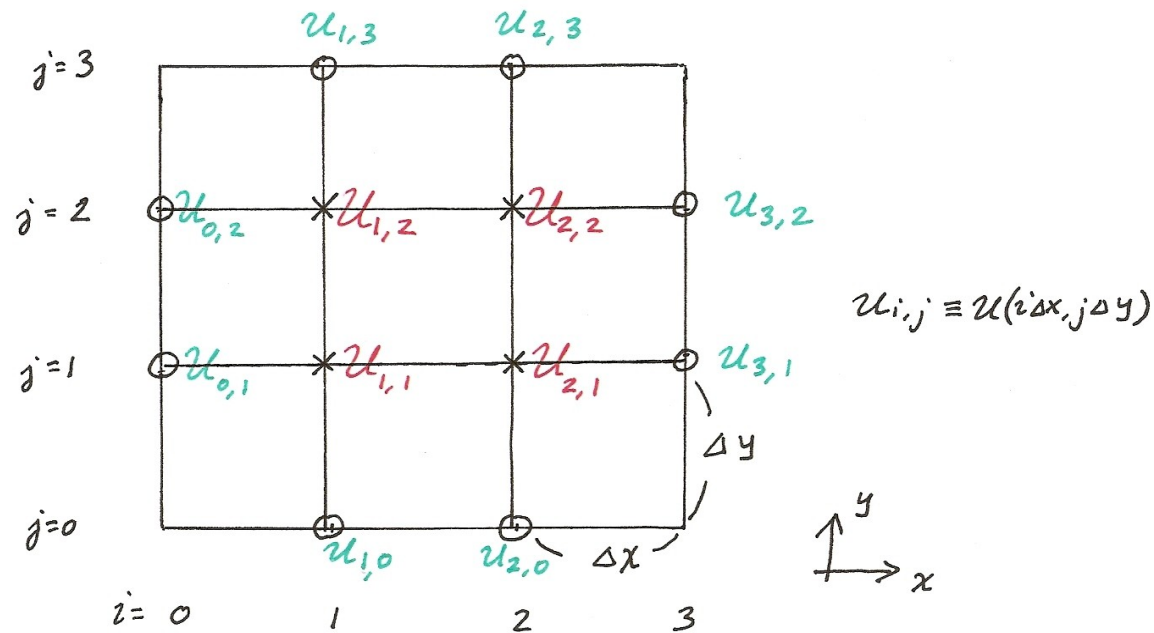
Example 1: Solve Laplace equation, $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$, for $u(x,y)$ defined on $x \in [0,1]$, $y \in [0, 1]$, with the boundary conditions

$$(I) u(x, 0) = 1 \quad (II) u(x,1) = 2 \quad (III) u(0,y) = 1 \quad (IV) u(1,y) = 2 .$$

The domain for the PDE is a square with 4 "walls" as illustrated in the following figure. The four boundary conditions are imposed to each of the four walls.



Consider a "toy" example with just a few grid points:



In the preceding diagram, the values of the variables in **green** are already given by the boundary conditions. The only unknowns are the **red** $u_{i,j}$ at the interior points. We have 4 unknowns, need 4 equations to determine their values. Let us first approximate the second partial derivatives in the PDE by a *2nd order central difference scheme*,

$$\left(\frac{\partial^2 u}{\partial x^2}\right)_{i,j} \approx \frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{(\Delta x)^2}, \quad (1)$$

$$\left(\frac{\partial^2 u}{\partial y^2}\right)_{i,j} \approx \frac{u_{i,j-1} - 2u_{i,j} + u_{i,j+1}}{(\Delta y)^2}. \quad (2)$$

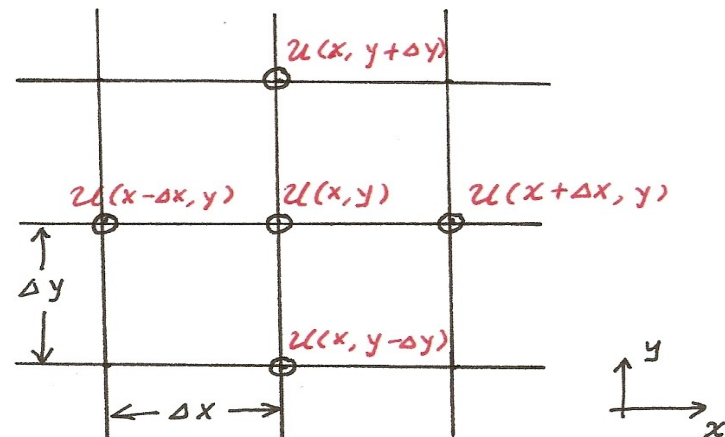
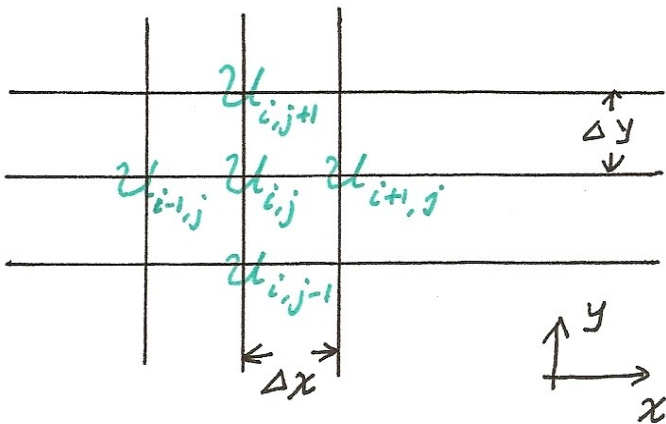
(Ex. 1 continued)

Equations (1) and (2) are the same as those for the ordinary 2nd derivatives, d^2u/dx^2 and d^2u/dy^2 , only that in Eq. (1) y is held constant (all terms in Eq. (1) have the same j) and in Eq. (2) x is held constant (all terms have the same i). For those who are not yet familiar with the index notation, Eqs. (1) and (2) are equivalent to

$$\left(\frac{\partial^2 u}{\partial x^2}\right) \approx \frac{u(x-\Delta x, y) - 2u(x, y) + u(x+\Delta x, y)}{(\Delta x)^2}, \quad (1a)$$

$$\left(\frac{\partial^2 u}{\partial y^2}\right) \approx \frac{u(x, y-\Delta y) - 2u(x, y) + u(x, y+\Delta y)}{(\Delta y)^2}. \quad (2a)$$

The correspondence between the two set of notations is illustrated in the following.



(Ex. 1 continued)

Plugging Eqs. (1) and (2) into the original Laplace equation, we obtain

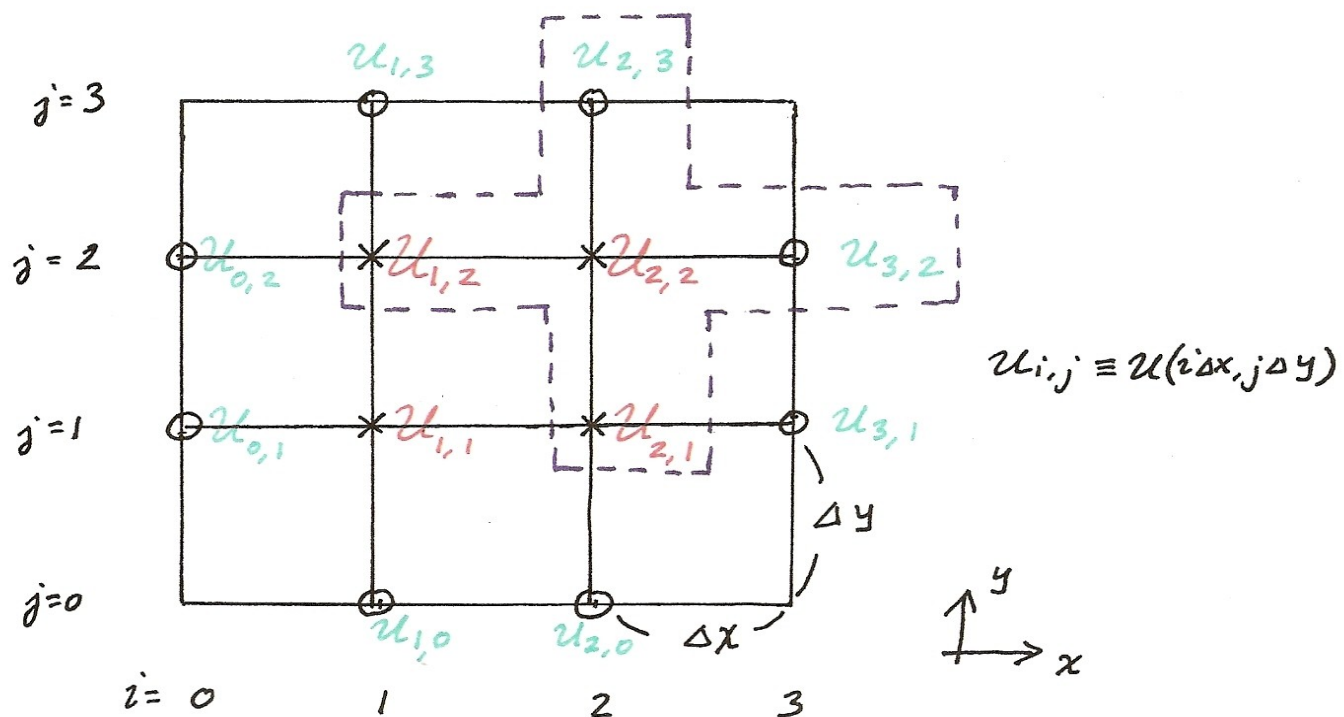
$$\frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{(\Delta x)^2} + \frac{u_{i,j-1} - 2u_{i,j} + u_{i,j+1}}{(\Delta y)^2} = 0, \text{ at the grid point } (i, j). \quad (3A)$$

For $\Delta x = \Delta y$, this equation can be rearranged into

$$-4u_{i,j} + u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} = 0, \text{ at the grid point } (i, j). \quad (3)$$

The distribution of the variables in Eq. (3) on the grid is illustrated in the diagrams in the preceding page. The partial derivatives, $\partial^2 u / \partial x^2 + \partial^2 u / \partial y^2$, can be evaluated by (3) at the grid point (i, j) using the discrete values of u at (i, j) itself (with weight of -4) and those at its 4 neighboring points - at left, right, top, and bottom. The diagram in the next page illustrates how this fits into the grid system of our problem. For example, at the grid point, $(i, j) = (2, 2)$, the terms in Eq. (3) are $u_{2,2}$ at center and $u_{2,3}$, $u_{2,1}$, $u_{1,2}$, and $u_{3,2}$ at top, bottom, left, and right of the grid point. The relevant grid points form a "cross" pattern.

(Ex. 1 continued)



$$-4u_{2,2} + u_{1,2} + u_{2,1} + \underbrace{u_{2,3} + u_{3,2}}_{\text{known from B.C.}} = 0$$

(Ex. 1 continued)

Using Eq. (3), we can now write the equations for $u_{i,j}$ at the four interior points,

$$\begin{aligned}
 -4 u_{1,1} + u_{1,2} + u_{2,1} + u_{0,1} + u_{1,0} &= 0 \\
 u_{1,1} - 4 u_{1,2} + u_{2,2} + u_{0,2} + u_{1,3} &= 0 \\
 u_{1,2} - 4 u_{2,2} + u_{2,1} + u_{2,3} + u_{3,2} &= 0 \\
 u_{1,1} + u_{2,2} - 4 u_{2,1} + u_{2,0} + u_{3,1} &= 0
 \end{aligned} \tag{4}$$

A quick reference for the relationships among the red and green symbols can be found in the preceding diagram. The red symbols correspond to the unknown $u_{i,j}$ at the interior points. The green ones are known values of $u_{i,j}$ given by the boundary conditions (see the original boundary conditions in p.3),

$$\begin{aligned}
 \text{(I) Bottom: } u_{1,0} = 1, u_{2,0} = 1 & \quad \text{(II) Top: } u_{1,3} = 2, u_{2,3} = 2 \\
 \text{(III) Left: } u_{0,1} = 1, u_{0,2} = 1 & \quad \text{(IV) Right: } u_{3,1} = 2, u_{3,2} = 2
 \end{aligned} \tag{5}$$

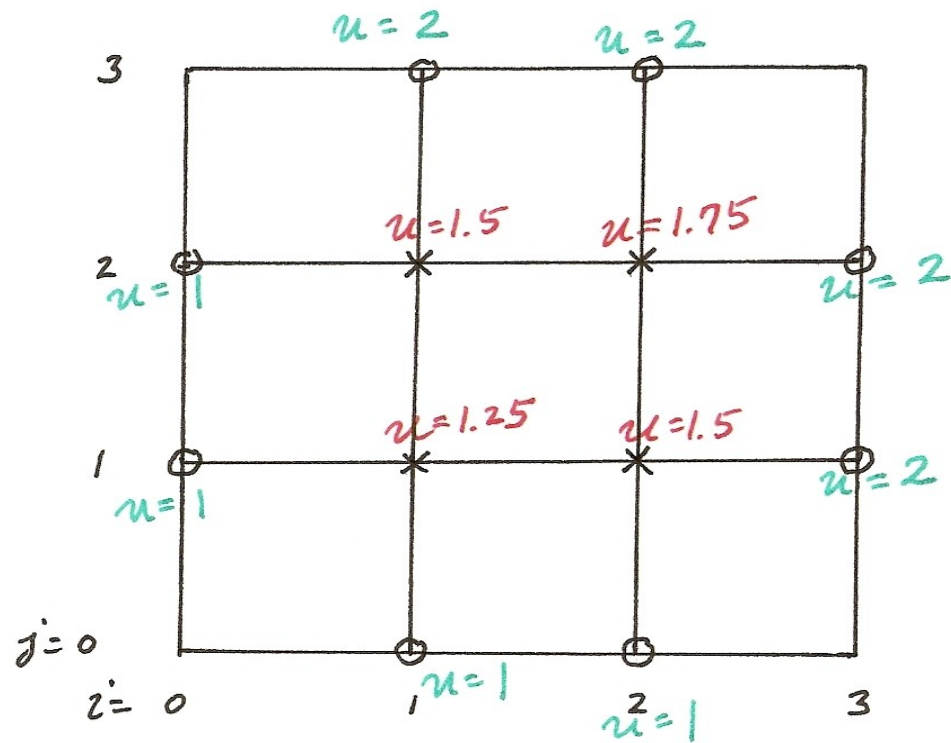
Moving the green symbols in Eq. (4) to the right hand side and replacing them with the known values given by the b.c. in Eq. (5), we obtain

$$\begin{pmatrix} -4 & 1 & 0 & 1 \\ 1 & -4 & 1 & 0 \\ 0 & 1 & -4 & 1 \\ 1 & 0 & 1 & -4 \end{pmatrix} \begin{pmatrix} u_{1,1} \\ u_{1,2} \\ u_{2,2} \\ u_{2,1} \end{pmatrix} = \begin{pmatrix} -2 \\ -3 \\ -4 \\ -3 \end{pmatrix}, \tag{6}$$

which can be readily solved to obtain the final solution, $(u_{1,1}, u_{1,2}, u_{2,2}, u_{2,1}) = (1.25, 1.5, 1.75, 1.5)$.

(Ex. 1 continued)

The solution is illustrated in the following figure. The behavior of the solution is as we expected: Constrained by the boundary conditions, The "temperature", u , decreases from the top right corner to lower left corner of the domain. Note that, unlike the matrix for the boundary value problems for ODE, the matrix in Eq. (6) is not strictly tridiagonal. It is however only slightly more complicated; We can discretize the system on a finer grid with even more grid points and yet there will always be just 3 non-zero elements in each row and each column of the matrix.



Case 2: Evolution equation defined on $t \in [0, \infty)$

Example 2: Solve the linear advection equation for $u(x, t)$,

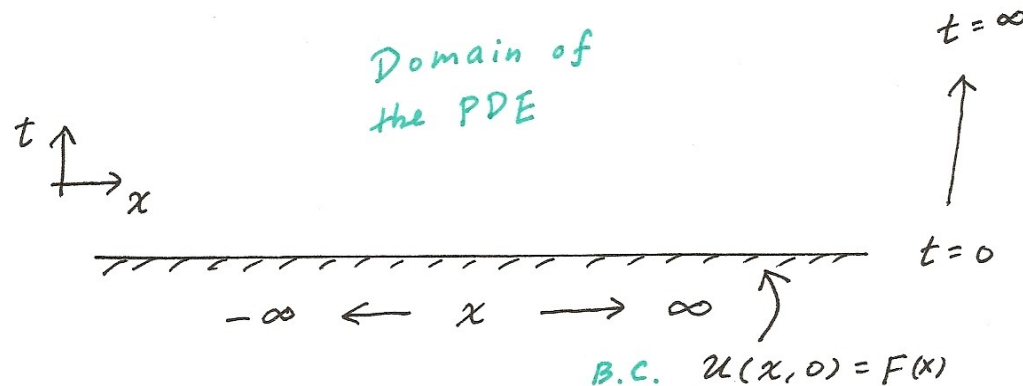
$$\frac{\partial u}{\partial t} = c \frac{\partial u}{\partial x} ,$$

defined on $x \in (-\infty, \infty)$, $t \in [0, \infty)$, and with the boundary condition,

$$(I) \quad u(x, 0) = F(x) .$$

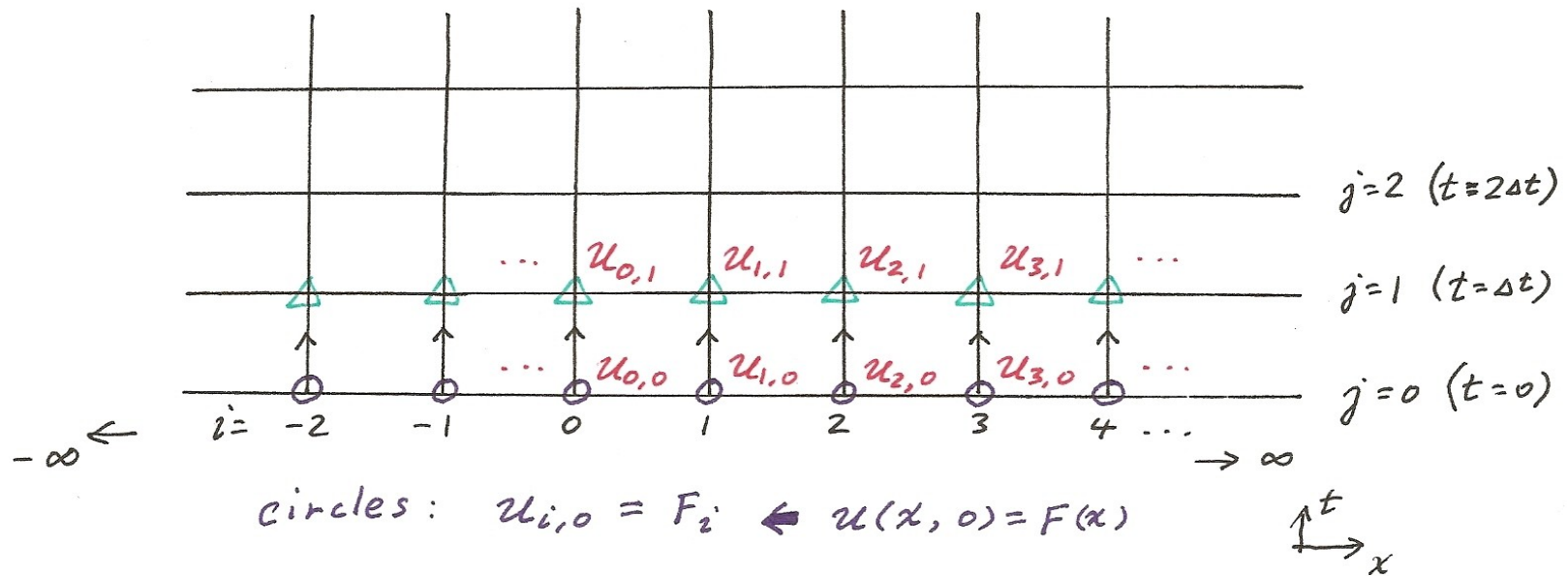
$F(x)$ will be given later as the discussion progresses.

Like in Example 1, we should discretize the system on a two-dimensional grid for x and t using the notation, $u_{i,j} \equiv u(i\Delta x, j\Delta t)$, $x_i \equiv i\Delta x$, and $t_j \equiv j\Delta t$. Unlike Example 1, here the domain for the PDE is unbounded in x , and semi-infinite in t (analogous to an initial value problem for ODE). There is only one "wall" at $t = 0$ along which the values of u are given by the boundary condition. See the following diagram.



(Ex. 2 continued)

The following diagram provides further detail for the grid. The values of $u_{i,0}$ at the grid points at the bottom ($t = 0$ or $j = 0$, marked by circles) are given by the boundary condition, $u_{i,0} = F_i$ (the discretized form of the boundary condition (I), where $F_i \equiv F(i\Delta x)$). From the bottom row with known values of u , we integrate the PDE forward in t ("upward" in the following diagram) to $t = \Delta t$ ($j = 1$) to obtain $u_{i,1}$, i.e., $u(x, \Delta t)$, marked by green triangles. The process then continues to the next level at $j = 2$ ($t = 2\Delta t$), and so on. In the diagram, the arrows that connect a circle to a triangle are only symbolic. Usually, the value of u at a triangle with $j = 1$ is determined by not only the value of u at the circle below it but also those at several neighboring circles. This will be clarified shortly.



\circ : given $\xrightarrow{\text{integration in } t \text{ for 1 step}}$ \triangle

(Ex. 2 continued)

To perform the integration in t , we discretize the PDE by approximating $\partial u/\partial t$ with the forward difference scheme, and $\partial u/\partial x$ with the central difference scheme (this combination is but one of many possible choices),

$$\left(\frac{\partial u}{\partial t}\right)_{i,j} \approx \frac{u_{i,j+1} - u_{i,j}}{(\Delta t)}, \quad (7)$$

$$\left(\frac{\partial u}{\partial x}\right)_{i,j} \approx \frac{u_{i+1,j} - u_{i-1,j}}{(2\Delta x)}. \quad (8)$$

The partial differentiation in Eq. (7) is performed with x held constant (the index i is the same for all terms in that equation). Likewise, t (or index j) is held constant in Eq. (8). Combining (7) and (8) we have

$$\frac{u_{i,j+1} - u_{i,j}}{(\Delta t)} = c \frac{u_{i+1,j} - u_{i-1,j}}{(2\Delta x)},$$

or

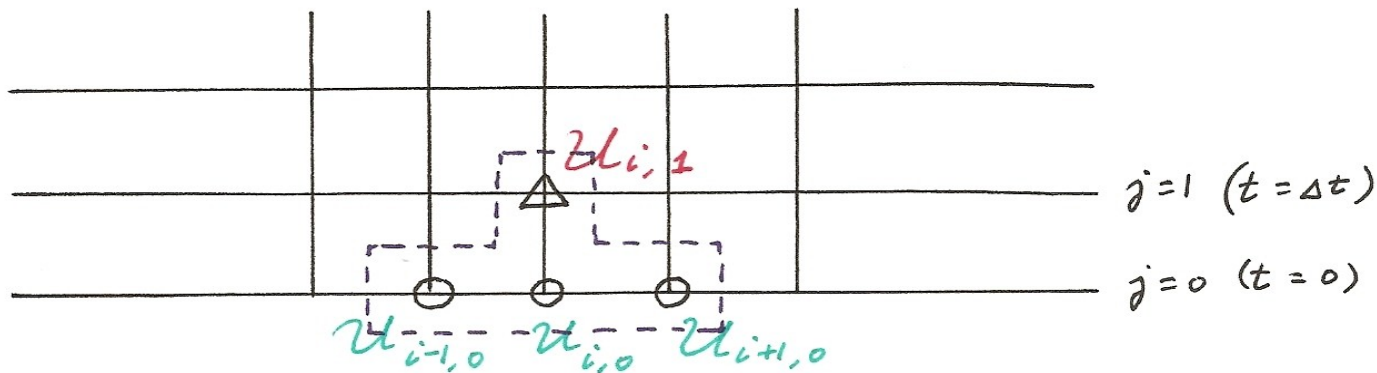
$$u_{i,j+1} = -\left(\frac{c\Delta t}{2\Delta x}\right)u_{i-1,j} + u_{i,j} + \left(\frac{c\Delta t}{2\Delta x}\right)u_{i+1,j}. \quad (9)$$

Defining $\alpha \equiv (c\Delta t)/(2\Delta x)$, Equation (9) can also be written as

$$u_{i,j+1} = -\alpha u_{i-1,j} + u_{i,j} + \alpha u_{i+1,j}. \quad (10)$$

(Ex. 2 continued)

The u in the left hand side of Eq. (10) is located at level $j+1$ (or $t = (j+1)\Delta t$), while those in right hand side are all located at level j (or $t = j\Delta t$). The situation is illustrated in the following diagram for $j = 0$. Here, $u_{i,1}$ at the level of $j = 1$ ($t = \Delta t$), marked by a triangle, is determined by $u_{i-1,0}$, $u_{i,0}$, and $u_{i+1,0}$ (marked by circles), located one level below it at $j = 0$ ($t = 0$). Since the values of u at the level of $j = 0$ are given by the boundary condition, $u_{i,1}$ is readily obtained from Eq. (10). Once all $u_{i,1}$ at the level of $j = 1$ are calculated, they can be used to determine $u_{i,2}$ at the next level (going one step upward in the diagram), and so on.



$$u_{i,1} = -\left(\frac{c\Delta t}{2\Delta x}\right) u_{i-1,0} + u_{i,0} + \left(\frac{c\Delta t}{2\Delta x}\right) u_{i+1,0}$$

↑ ↑
All are known
from B.C.

(Ex. 2 continued)

Let's try an example with $c = 1$, $\Delta x = 0.2$, $\Delta t = 0.1$ ($\Rightarrow \alpha = 0.25$ in Eq. (10)), and with the boundary condition,

$$\begin{aligned} u_{4,0} &= 1 \quad , \\ u_{i,0} &= 0 \quad \text{for all } i \neq 4. \end{aligned} \tag{11}$$

See the plot in p.17 for the "initial state" given by Eq. (11). With the given c , Δx , and Δt , Eq. (10) becomes

$$u_{i,j+1} = -0.25u_{i-1,j} + u_{i,j} + 0.25u_{i+1,j} \quad . \tag{12}$$

The equation that's needed to integrate Eq. (12) forward from $t = 0$ to $t = \Delta t$ (i.e., from $j = 0$ to $j = 1$) is

$$u_{i,1} = -0.25u_{i-1,0} + u_{i,0} + 0.25u_{i+1,0} \quad .$$

Clearly, $u_{i,1}$ is zero for all i except the following three,

$$\begin{aligned} u_{3,1} &= -0.25u_{2,0} + u_{3,0} + 0.25u_{4,0} = 0.25 \quad , \\ u_{4,1} &= -0.25u_{3,0} + u_{4,0} + 0.25u_{5,0} = 1 \quad , \\ u_{5,1} &= -0.25u_{4,0} + u_{5,0} + 0.25u_{6,0} = -0.25 \quad . \end{aligned} \tag{13}$$

The results in (13) are our solution of the PDE at $t = \Delta t = 0.1$. They can be used to integrate the PDE forward to $t = 2\Delta t = 0.2$ ($j = 2$), and so on. Just as a further demonstration, at $j = 2$ we have

(Ex. 2 continued)

$$u_{2,2} = -0.25 u_{1,1} + u_{2,1} + 0.25 u_{3,1} = 0.0625 \text{ ,}$$

$$u_{3,2} = -0.25 u_{2,1} + u_{3,1} + 0.25 u_{4,1} = 0.5 \text{ ,}$$

$$u_{4,2} = -0.25 u_{3,1} + u_{4,1} + 0.25 u_{5,1} = 0.875 \text{ ,}$$

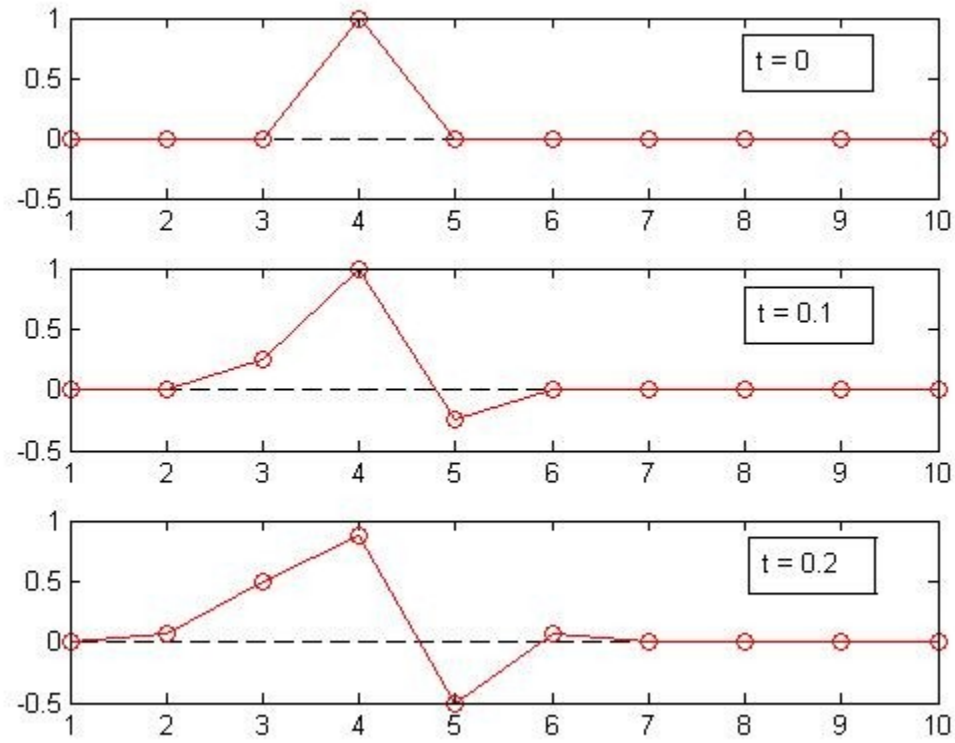
$$u_{5,2} = -0.25 u_{4,1} + u_{5,1} + 0.25 u_{6,1} = -0.5 \text{ ,}$$

$$u_{6,2} = -0.25 u_{5,1} + u_{6,1} + 0.25 u_{7,1} = 0.0625 \text{ .}$$

All other $u_{i,2}$ with $i > 6$ or $i < 2$ are zero. The plot in next page shows the "initial state" and the solutions at $t = \Delta t$ and $t = 2\Delta t$ (i.e., u_{ij} at $j = 0, 1$, and 2).

Lastly, note that the finite difference scheme used in this example is far from the best. It is chosen for its simplicity. In the analytic solution, the shape of the initial state should remain the same at $t = 0, 0.1$, and 0.2 . Moreover, u would not become negative at any location. As it turns out, it is not trivial to fix these problems even with more sophisticated numerical schemes. This is beyond the scope of our discussion.

(Ex. 2 continued)



The number on the abscissa is the index " i ". The three panels from top to bottom are $j = 0, 1,$ and 2 (or $t = 0, 0.1,$ and 0.2).

A Matlab program that was used to solve the PDE and produce the plot is listed in next page.

(Ex. 2 continued)

```
% Matlab code for Example 2 for PDE
% May 7, 2015
% -----
% Define and initialize the variables
for i = 1:10
    xi(i) = i;
    for j = 1:3
        uij(i,j) = 0;
    end
end
%
% The boundary condition (which essentially defines the "initial state")
%
uij(4,1) = 1;
%
% integration to t = 0.1 and 0.2
%
for j = 1:2
    for i = 2:9
        uij(i,j+1) = -0.25*uij(i-1,j)+uij(i,j)+0.25*uij(i+1,j);
    end
end
%
% making the plots for t = 0, 0.1, and 0.2
%
for i = 1:10
    u0(i) = uij(i,1);
    u1(i) = uij(i,2);
    u2(i) = uij(i,3);
    z(i) = 0;
end
subplot(3,1,1);plot(xi,z,'k--',xi,u0,'r-o');axis([1 10 -0.5 1])
subplot(3,1,2);plot(xi,z,'k--',xi,u1,'r-o');axis([1 10 -0.5 1])
subplot(3,1,3);plot(xi,z,'k--',xi,u2,'r-o');axis([1 10 -0.5 1])
```